MiR Hook™ 200 Mounting guide
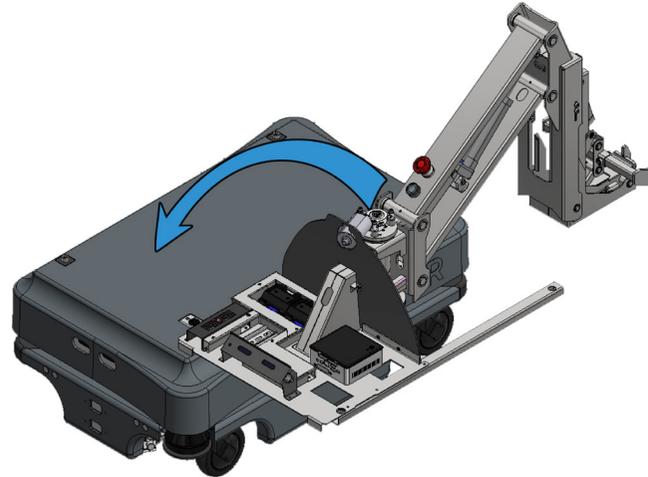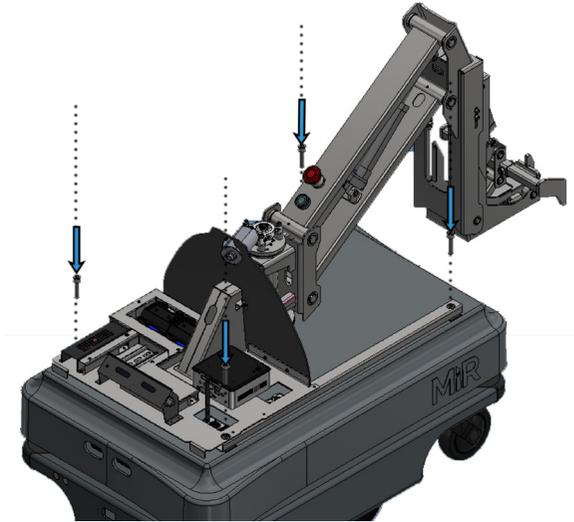
①

MiR200 robot

Hook

② Remove the hook cover and lift the hook onto the robot fitting the frame holes above the four mooring holes on the robot.
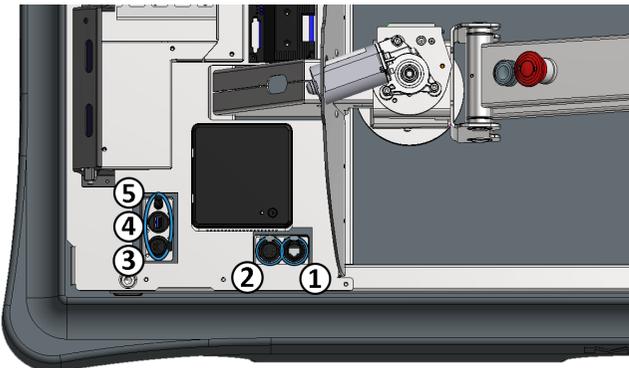

③ Mount the frame with the 4 bolts.
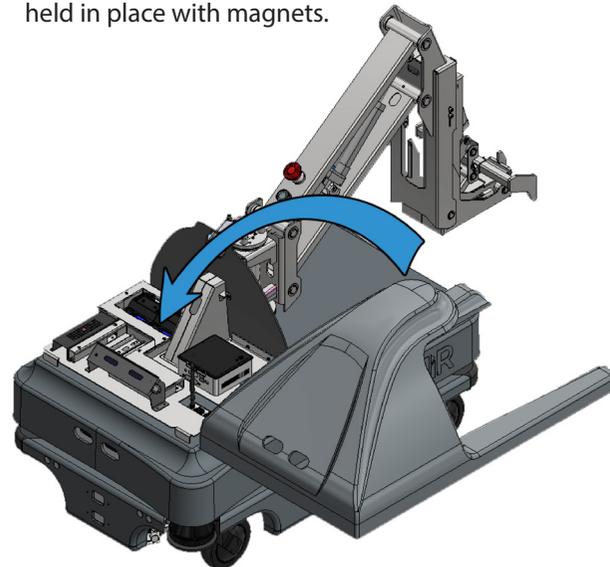Tighten the bolts to a torque of 47 [Nm] / [34.5 ft-lb].

④ Connect cables and mount the antenna:
1. Network cable (from robot to hook PC)
2. Application hardware cable
3. Emergency stop cable
4. USB cable for top camera
5. Antenna connector

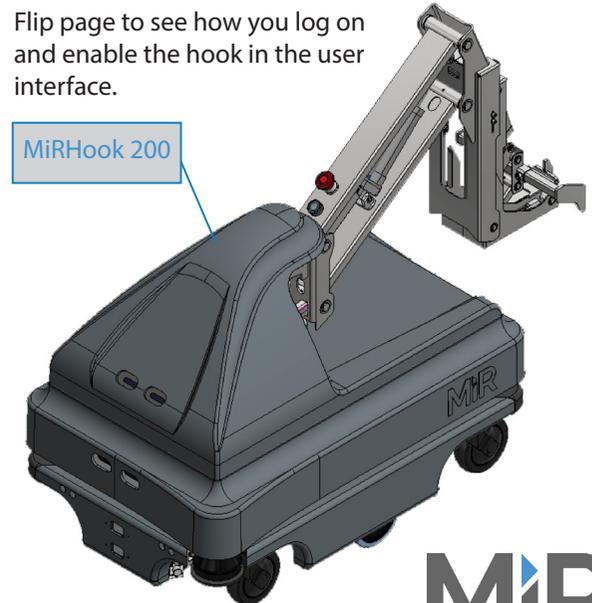
⑤ Place the cover on top of the hook frame. The cover is held in place with magnets.

⑥ Flip page to see how you log on and enable the hook in the user interface.

MiRHook 200

MiR
MOBILE INDUSTRIAL ROBOTS

MiRHook™ 200 Connecting: Robot Interface 2.0

① Connect to WiFi:

Turn on the robot. On a PC or tablet, go to the WiFi menu, find the name of your robot and connect to it.

② Open robot user interface:

Open a browser and go to mir.com. Log in with username: **distributor** and password: **distributor**.

③ Enable Hook feature:

Navigate to **Features** (System > Settings > Features) and set **Hook** to True.

④ Set up hook with carts:

In the **main** menu, a new **Hook** icon appears. This is where all settings to prepare the robot for automatic pick up and delivery of carts are made.

See the MiRHook user guide for more information.