# MiRHook<sup>™</sup> 200 Mounting guide



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Remove the hook cover and lift the hook onto the robot fitting the frame holes above the four mooring holes on the robot.



Place the cover on top of the hook frame. The cover is held in place with magnets.

Mount the frame with the 4 bolts. Tighten the bolts to a torque of 47 [Nm] / [34.5 ft-lb].



Flip page to see how you log on and enable the hook in the user interface. MiRHook 200



## MiRHook<sup>™</sup> 200 Connecting: Robot Interface 2.0

(3)

### Connect to WiFi:

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(2)

Turn on the robot. On a PC or tablet, go to the WiFi menu, find the name of your robot and connect to it.

#### Open robot user interface:

Open a browser and go to mir.com. Log in with username: **distributor** and password: **distributor**.

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password			
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be given to you by either the robot administrator or found in the robot	•••••		
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If you don't have a username and password, please contact the robot	of Log in		
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MiR software version: 2.0.1 Copyright © Mobile Industrial Robots ApS 2016 - 2017.						

#### **Enable Hook feature:**

Navigate to **Features** (System > Settings > Features) and set **Hook** to True.



#### Set up hook with carts:

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In the **main** menu, a new **Hook** icon appears. This is where all settings to prepare the robot for automatic pick up and delivery of carts are made.

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